Newtonian and general relativistic orbits with small eccentricities on 2D surfaces

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## Outline

- The elliptical orbits of Newtonian gravitation
- The 2D surfaces that generate Newtonian orbits with small eccentricities
- Precessing elliptical orbits of GR with small eccentricities
- The 2D surfaces that generate general relativistic orbits with small eccentricities


## Einstein's theory of general relativity

$$
G_{\mu \nu}=\frac{8 \pi G}{c^{4}} T_{\mu \nu}
$$

- $G_{\mu \nu}$ describes the curvature of spacetime
- $T_{\mu \nu}$ describes the matter \& energy in spacetime

> Matter tells space how to curve, space tells matter how to move.


Sean M. Carrol, Spacetime and Geometry: An Introduction to Einstein's General Relativity (Addison Wesley, 2004)

## Einstein's theory of general relativity

Consider a spherically-symmetric, non-rotating massive object...

## Embedding diagram ( $t=t_{0}, \theta=\pi / 2$ )..

- 2D equatorial 'slice' of the 3D space at one moment in time

$$
z(r)=2 \sqrt{\frac{2 G M}{c^{2}}\left(r-\frac{2 G M}{c^{2}}\right)}
$$

Is there a warped 2D surface that will yield the orbits of planetary motion?

The Lagrangian in spherical-polar coordinates with a Newtonian potential

- is of the form..

$$
L=\frac{1}{2} m\left(\dot{r}^{2}+r^{2} \dot{\phi}^{2}\right)+\frac{G m M}{r}
$$

- where we set $\theta=\pi / 2$ and a dot refers to a time derivative.
- For the azimuthal-coordinate..

$$
\frac{\partial L}{\partial \phi}-\frac{d}{d t} \frac{\partial L}{\partial \dot{\phi}}=0 \quad \text { yields } \quad r^{2} \dot{\phi}=\ell \quad \text {-Kepler's } 2^{\text {nd }} \text { Law }
$$

## The Lagrange equations of motion

- For the radial-coordinate..

$$
\frac{\partial L}{\partial r}-\frac{d}{d t} \frac{\partial L}{\partial \dot{r}}=0
$$

- yields the equation of motion for an object of mass m..

$$
\ddot{r}-\frac{\ell^{2}}{r^{3}}+\frac{G M}{r^{2}}=0
$$

- Using the differential operator..

$$
\frac{d}{d t}=\frac{\ell}{r^{2}} \frac{d}{d \phi}
$$

* can be written in the form..


## The equation of motion

- For the radial-coordinate..

$$
\frac{d^{2} r}{d \phi^{2}}-\frac{2}{r}\left(\frac{d r}{d \phi}\right)^{2}-r+\frac{G M}{\ell^{2}} r^{2}=0
$$

- yields the conic sections..

- where $\ell^{2}=G M r_{0}$
- and $\varepsilon$ is the eccentricity of the orbit.
http://www.controlbooth.com/threads/cyc-color-wash-using-fresnels.30704/


## The radial equation of motion

- the exact solution..

$$
r(\phi)_{e x}=\frac{r_{0}}{(1+\varepsilon \cos \phi)}
$$

- for small eccentricities..

$$
r(\phi)_{a p p} \simeq r_{0}(1-\varepsilon \cos \phi)
$$

| Planets | $r_{\mathrm{o}}(\mathrm{m})$ | $\varepsilon$ | \% error |
| :--- | :--- | ---: | ---: |
| Mercury | $5.79^{*} 10^{10}$ | 0.2056 | 4.227 |
| Venus | $1.08^{*} 10^{10}$ | 0.0068 | 0.005 |
| Earth | $1.50^{*} 10^{11}$ | 0.0167 | 0.028 |
| Mars | $2.28^{*} 10^{11}$ | 0.0934 | 0.872 |
| Jupiter | $7.78^{*} 10^{11}$ | 0.0483 | 0.233 |
| Saturn | $1.43^{*} 10^{12}$ | 0.056 | 0.314 |
| Uranus | $2.87^{*} 10^{12}$ | 0.0461 | 0.213 |
| Neptune | $4.50^{*} 10^{12}$ | 0.01 | 0.01 |

$$
\begin{aligned}
\% \text { error } & =\frac{\left|r_{e x}-r_{a p p}\right|}{r_{e x}} * 100 \% \\
& =\varepsilon^{2} \cos \phi * 100 \%
\end{aligned}
$$

## Notice:

-     * yields an excellent approximation for the solar system planets!


## Kepler's $3^{\text {rd }}$ Law

- Setting $\dot{r}=\ddot{r}=0$ and using $\dot{\phi}=2 \pi / T$ for circular orbits...

$$
T^{2}=\left(\frac{4 \pi^{2}}{G}\right) \cdot \frac{r^{3}}{M}
$$

## Notice:

- Kepler's $3^{\text {rd }}$ Law is independent of $m$ !



## An object orbiting on a 2D cylindricallysymmetric surface

- is described by a Lagrangian of the form..

$$
L=\frac{1}{2} m\left(\dot{r}^{2}+r^{2} \dot{\phi}^{2}+\dot{z}^{2}\right)+\frac{1}{2} I \omega^{2}-m g z
$$

- Now, for the orbiting object..

$$
\begin{aligned}
I=\alpha m R^{2} \text { and } \omega^{2}=v^{2} / R^{2} \quad \text { so } \frac{1}{2} I \omega^{2}=\frac{1}{2} \alpha m v^{2} \\
\text { where } \left.\begin{array}{rl}
\alpha & =2 / 5 \text { for a rolling sphere, } \\
\alpha & =0 \quad \text { for a sliding object. }
\end{array} . \begin{array}{rl} 
\\
\text { a }
\end{array}\right)
\end{aligned}
$$

- The orbiting object is constrained to reside on the surface..

$$
z=z(r)
$$

## The Lagrange equations of motion

- For the azimuthal-coordinate..

$$
\frac{\partial L}{\partial \phi}-\frac{d}{d t} \frac{\partial L}{\partial \dot{\phi}}=0 \quad \text { yields } \quad r^{2} \dot{\phi}=\ell /(1+\alpha)
$$

- For the radial-coordinate..

$$
\frac{\partial L}{\partial r}-\frac{d}{d t} \frac{\partial L}{\partial \dot{r}}=0
$$

- yields the equation of motion for the orbiting object..

$$
\left(1+z^{\prime 2}\right) \ddot{r}+z^{\prime} z^{\prime \prime} \dot{r}^{2}-\frac{\tilde{\ell}^{2}}{r^{3}}+\tilde{g} z^{\prime}=0 \quad \text { where } \begin{aligned}
& \tilde{\ell} \equiv \ell /(1+\alpha) \\
& \tilde{g} \equiv g /(1+\alpha)
\end{aligned}
$$

## The Lagrange equation of motion

Compare the equation of motion for the orbiting object..

$$
\left(1+z^{\prime 2}\right) \ddot{r}+z^{\prime} z^{\prime \prime} \dot{r}^{2}-\frac{\tilde{\ell}^{2}}{r^{3}}+\tilde{g} z^{\prime}=0
$$

- to the equation of motion for planetary orbits..

$$
\ddot{r}-\frac{\ell^{2}}{r^{3}}+\frac{G M}{r^{2}}=0
$$

## * will NOT yield Newtonian orbits on ANY cylindricallysymmetric surface, except in the special case of circular orbits.

## The Lagrange equation of motion

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- to the equation of motion for planetary orbits..

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$$

* will NOT yield Newtonian orbits on ANY cylindricallysymmetric surface, except in the special case of circular orbits.


## The radial equation of motion

- Using the differential operator, the radial equation becomes..

$$
\left(1+z^{\prime 2}\right) \frac{d^{2} r}{d \phi^{2}}+\left[z^{\prime} z^{\prime \prime}-\frac{2}{r}\left(1+z^{\prime 2}\right)\right]\left(\frac{d r}{d \phi}\right)^{2}-r+\frac{\tilde{g}}{\tilde{\ell}^{2}} z^{\prime} r^{4}=0
$$

- For nearly circular orbits with small eccentricities..

$$
r(\phi)=r_{0}(1-\varepsilon \cos (\nu \phi))
$$

where $r_{0} \& \nu$ are parameters.

## Notice:

- when $\nu=1$, stationary elliptical orbits
- when $\nu \neq 1$, precessing elliptical orbits.



## The radial equation of motion

- We find the solution, to $1^{\text {st }}$ order in the eccentricity, when..

$$
\begin{aligned}
\tilde{\ell}^{2} & =\tilde{g} r_{0}^{3} z_{0}^{\prime} \\
z_{0}^{\prime}\left(1+z_{0}^{\prime 2}\right) \nu^{2} & =3 z_{0}^{\prime}+r z_{0}^{\prime \prime}
\end{aligned}
$$

For $z(r) \propto-\frac{1}{r^{n}} \ldots$

- Precessing elliptical orbits when $n<2$
- Stationary elliptical orbits, for certain radii, when $n<1$
- No stationary elliptical orbits when $n=1$ !


## The 2D surface that generates Newtonian orbits

- To find the 2D surface that yields stationary elliptical orbits with small eccentricities for all radii, solve...

$$
z^{\prime}\left(1+z^{\prime 2}\right)=3 z^{\prime}+r z^{\prime \prime}
$$

- The solution for the slope of the surface is..

$$
\frac{d z}{d r}=\sqrt{2}\left(1+\kappa r^{4}\right)^{-1 / 2}
$$

where $\kappa$ is an arbitrary integration constant

Notice:

-     * is independent of spin of orbiting object.
- When $\kappa=0$, * becomes the equation of an inverted cone with slope $\sqrt{2}$.


## The 2D surface that generates Newtonian orbits

- Integrating yields the shape function...

$$
z(r)=-\sqrt{2}\left(-\frac{1}{\kappa}\right)^{1 / 4} F\left(\sin ^{-1}\left(-\kappa r^{4}\right)^{1 / 4},-1\right)
$$

- where $F(a, b)$ is an elliptic integral of the $1^{\text {st }} k i n d$.

Notice:


- This 2D surface will generate stationary elliptical orbits with small eccentricities for all radii!


## Kepler's $3^{\text {rd }}$ Law

- Setting $\dot{r}=\ddot{r}=0$ and using $\dot{\phi}=2 \pi / T$ for circular orbits...

$$
T^{2}=\left(\frac{2 \sqrt{2} \pi^{2}}{\tilde{g}}\right) r \sqrt{1+\kappa r^{4}}
$$

- Notice that when $\kappa r^{4} \ll 1$..


$$
T^{2} \propto r \quad \text { - Kepler-like relation for that of an inverted cone. }
$$

- and when $\kappa r^{4} \gg 1$..

$$
T^{2} \propto r^{3} \text { - Kepler's } 3^{\text {rd }} \text { Law of planetary motion. }
$$

## Precessing elliptical orbits in GR with small eccentricities

- The eqn of motion for an object orbiting about a non-rotating, spherically-symmetric object of mass $M$ in GR is..

$$
\ddot{r}-\frac{\ell^{2}}{r^{3}}+\frac{G M}{r^{2}}+\frac{3 G M \ell^{2}}{c^{2} r^{4}}=0
$$

- where a dot refers to a derivative w.r.t. proper time.
- Using the differential operator, * becomes..

$$
\frac{d^{2} r}{d \phi^{2}}-\frac{2}{r}\left(\frac{d r}{d \phi}\right)^{2}-r+\frac{G M}{\ell^{2}} r^{2}+\frac{3 G M}{c^{2}}=0
$$

- we choose a solution of the form..

$$
r(\phi)=r_{0}(1-\varepsilon \cos (\nu \phi)) \quad \text { where } r_{0} \& \nu \text { are parameters. }
$$

## Precessing elliptical orbits in GR with small eccentricities

- We find the solution, to $1^{\text {st }}$ order in the eccentricity, when..

$$
\begin{aligned}
& \ell^{2}=G M r_{0}\left(1-\frac{3 G M}{c^{2} r_{0}}\right)^{-1} \\
& \nu^{2}=1-\frac{6 G M}{c^{2} r_{0}}
\end{aligned}
$$

| Planets | $r_{\mathrm{o}}(\mathrm{m})$ | $\varepsilon$ | $6 G M / \mathrm{c}^{2} r_{o}$ |
| :---: | :---: | :---: | :---: |
| Mercury | $5.79^{*} 10^{10}$ | 0.2056 | $1.53^{*} 10^{-7}$ |
| Venus | $1.08^{*} 10^{10}$ | 0.0068 | $8.19^{*} 10^{-7}$ |
| Earth | $1.50^{*} 10^{11}$ | 0.0167 | $5.90^{*} 10^{-8}$ |
| Mars | $2.28^{*} 10^{11}$ | 0.0934 | $3.88^{*} 10^{-8}$ |
| Jupiter | $7.78^{*} 10^{11}$ | 0.0483 | $1.14^{*} 10^{-8}$ |
| Saturn | $1.43^{*} 10^{12}$ | 0.056 | $6.19^{*} 10^{-9}$ |
| Uranus | $2.87^{*} 10^{12}$ | 0.0461 | $3.08^{*} 10^{-9}$ |
| Neptune | $4.50^{*} 10^{12}$ | 0.01 | $1.97^{*} 10^{-9}$ |

## Notice:

- Deviation from closed elliptical orbits increases with decreasing $r_{0}$.
- When $r_{0}<6 G M / c^{2}, \nu$ becomes complex: elliptical orbits not allowed
- When $r_{0}<3 G M / c^{2}, \nu \& \ell$ become complex: no circular orbits.


## The 2D surfaces that generates general relativistic orbits

- To find the 2D surface that yields precessing elliptical orbits with small eccentricities for all radii, solve...

$$
z^{\prime}\left(1+z^{\prime 2}\right) \nu=3 z^{\prime}+r z^{\prime \prime} \quad \text { with } \quad \nu=\sqrt{1-\frac{6 G M}{c^{2} r_{0}}}
$$

- The solution for the slope of the surface is..

$$
\frac{d z}{d r}=\sqrt{\frac{2+\beta}{1-\beta}} \cdot\left(1+\kappa r^{2(2+\beta)}\right)^{-1 / 2} \quad \text { where } \beta \equiv 6 G M / c^{2} r_{0}
$$

Notice:

- dependent on central mass, $M$, and average radius of orbit, $r_{0}$.
- depends on $\beta$ in both overall factor and in the power.
- Slope diverges as $\beta \rightarrow 1$


## Compare the 2D surfaces...

- Slope that generates Newtonian stationary elliptical orbits..

$$
\frac{d z}{d r}=\sqrt{2}\left(1+\kappa r^{4}\right)^{-1 / 2}
$$

- Slope that generates the GR precessing elliptical orbits...

$$
\frac{d z}{d r}=\sqrt{\frac{2+\beta}{1-\beta}} \cdot\left(1+\kappa r^{2(2+\beta)}\right)^{-1 / 2}
$$

where $\beta \equiv 6 G M / c^{2} r_{0}$

## Notice:

- They agree when $\beta \rightarrow 0$.
- GR offers a tiny correction for the orbits of the solar system planets.

| Planets | $r_{0}(\mathrm{~m})$ | $\varepsilon$ | $\beta$ |
| :--- | :---: | :---: | :---: |
| Mercury | $5.79^{*} 10^{10}$ | 0.2056 | $1.53^{*} 10^{-7}$ |
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